

QUIVER VARIETIES AND QUANTUM KNIZHNIK–ZAMOLODCHIKOV EQUATION

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ABSTRACT. We show how equivariant volumes of tensor product quiver varieties of type A are given by matrix elements of vertex operators of centrally extended doubles of Yangians, and how they satisfy in some cases the rational, level 1, quantum Knizhnik–Zamolodchikov equation.

1. INTRODUCTION

It is increasingly clear that a deep connection exists between generalized cohomology theories and quantum integrable systems, as first pointed out in [5]. The simplest example is that rational quantum integrable systems should be related to (equivariant) cohomology. Such a connection somewhat accidentally reappeared in [12, 2] in the study of certain solutions of the quantum Knizhnik–Zamolodchikov equation. One of the objectives of this short paper is to revisit this connection in view of recent developments, in particular of the work [13], which provides a natural framework for it. The most basic ingredient in the definition of a quantum integrable system is to provide a solution of the Yang–Baxter equation, the so-called R -matrix. And indeed, [13] gives a “recipe” to compute the R -matrix in terms of certain algebro-geometric data. Conversely, in [12, 2], starting from certain quantum integrable models, algebraic varieties were introduced in such a way that the integrable model performed computations in equivariant cohomology on the latter. These two approaches are closely related, and in fact, among the equations defining the quantum Knizhnik–Zamolodchikov equation, one finds the so-called exchange relation which is a direct corollary of the definition of the R -matrix given in [13].

In the present work, we extend the study that was performed in [2, 21] to arbitrary Nakajima quiver varieties of type A. In section 2, we define these quiver varieties and give an explicit description (only available in type A) which is particularly convenient for explicit computations. In section 3, we first discuss the exchange relation and the definition of the R -matrix. We then introduce a key technical tool, which are Vertex Operators for a centrally extended double of a Yangian. We proceed to show that equivariant volumes of tensor product quiver varieties are equal to matrix elements of these Vertex Operators, and conclude that in some cases they satisfy the quantum Knizhnik–Zamolodchikov equation. Since the presentation is rather sparse on details, an example is fully worked out in appendix A. In particular, this paper is not meant to be fully rigorous mathematically, and some proofs are sketched or skipped, trying to focus on the main ideas rather than on technicalities.

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2. QUIVER VARIETIES

We briefly define here the relevant geometric objects, and refer to the abundant literature for details, in particular the work of Nakajima [15, 16, 17, 18] and the lecture notes [4] and references therein.

2.1. Definition. Given two sequences of finite-dimensional vector spaces V_a and W_a , with dimensions $v = (v_a)$ and $w = (w_a)$, $a = 1, \dots, k-1$, we define the corresponding Nakajima quiver variety of type A_{k-1} as the quotient of the space of linear maps $(B_{a,a+1}, B_{a+1,a}, i_a, j_a)$ in

$$\bigoplus_{a=1}^{k-2} (\text{Hom}(V_a, V_{a+1}) \oplus \text{Hom}(V_{a+1}, V_a)) \oplus \bigoplus_{a=1}^{k-1} (\text{Hom}(W_a, V_a) \oplus \text{Hom}(V_a, W_a))$$

subject to the moment map conditions $\mu = 0$, where

$$\mu = (B_{a,a-1}B_{a-1,a} - B_{a,a+1}B_{a+1,a} + i_a j_a)_{a=1, \dots, k-1}$$

(where conventionally an index k or 0 means that the term is absent) by the natural action of $G_v = \prod_{a=1}^{k-1} GL(V_a)$, namely

$$(g_a) \in G_v : (B_{a,a+1}, B_{a+1,a}, i_a, j_a) \mapsto (g_{a+1}B_{a,a+1}g_a^{-1}, g_aB_{a+1,a}g_{a+1}^{-1}, g_a i_a, j_a g_a^{-1})$$

The algebro-geometric quotient is obtained by considering the subring of G_v -invariant functions:

$$\mathfrak{M}_0(v, w) = \mu^{-1}(0) // G_v$$

$\mathfrak{M}_0(v, w)$ is an affine singular variety.

Most of the time $\mathfrak{M}_0(v, w)$ will be sufficient for our purposes, but at one point we shall need to consider the GIT quotient

$$\mathfrak{M}(v, w) = \mu^{-1}(0) //_{\theta} G_v$$

where θ is some appropriate character, see e.g. [17, 4]. $\mathfrak{M}(v, w)$ is smooth quasi-projective.

When there is no risk of confusion, we simply write $\mathfrak{M}_0 = \mathfrak{M}_0(v, w)$ and so on.

2.2. Combinatorial data. Associate to w and v the $SL(k)$ weights $\mu = \sum_{a=1}^{k-1} w_a \omega_a$ and $\lambda = \sum_{a=1}^{k-1} w_a \omega_a - \sum_{a=1}^{k-1} v_a \alpha_a$, where the ω_a are the fundamental weights of $SL(k)$ and α_a are its simple roots. We shall assume in what follows that λ is a weight of the irreducible representation of $SL(k)$ with highest weight μ .

Also, we shall need to lift μ and λ to $GL(k)$ weights. This is not unique, but there is an obvious way which is to leave the k^{th} weight of μ to be zero.¹ The resulting $GL(k)$ weights are conveniently described as arrays of boxes; as an example,

$$\begin{array}{lcl} w = (2, 1, 3) & \rightarrow & \mu = 2 \begin{array}{|c|} \hline \square \\ \hline \end{array} + \begin{array}{|c|} \hline \square \\ \hline \end{array} + 3 \begin{array}{|c|} \hline \square \\ \hline \end{array} = \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \\ \\ v = (1, 0, 1) & \rightarrow & \lambda = \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \rangle 1 = \begin{array}{|c|c|c|c|c|} \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \square & \square & \square & \square & \square \\ \hline \end{array} \end{array}$$

¹The effect of making another choice of lift to $GL(k)$ will be discussed in sect. 3.2.3.

Moreover, for the sake of simplicity, we shall also assume in what follows that λ is dominant². The natural morphism $p : \mathfrak{M}(v, w) \rightarrow \mathfrak{M}_0(v, w)$ is then surjective, and a resolution of singularities of $\mathfrak{M}_0(v, w)$.

2.3. Transverse slice of nilpotent orbit closures. There are several alternative descriptions of \mathfrak{M}_0 in terms of transverse slices of nilpotent orbit closures. One is particularly convenient for our purposes: the slice of Mirković and Vybornov [14].

Denote $N = \sum_{a=1}^{k-1} w_a$, $M = \sum_{a=1}^{k-1} a w_a$. Starting from μ and λ , we associate two new sequences of integers, $m = (m_1, \dots, m_N)$ and $\ell = (\ell_1, \dots, \ell_N)$ respectively, as follows (see also [14, sect. 5.1]). They are an arbitrary permutation of the sequence of numbers of boxes in each column of their box diagram as defined in previous section (where for simplicity of notation we always take ℓ to be of length N , i.e., possibly pad it with zeroes). Let us immediately mention that the ordering of ℓ is irrelevant; however, the ordering of m leads to isomorphic but distinct constructions, and it is convenient to retain this freedom.

In the example above, m and ℓ are permutations of $(3, 3, 3, 2, 1, 1)$ and $(4, 3, 2, 2, 2, 0)$, respectively.

Note $\sum_{i=1}^N m_i = \sum_{i=1}^N \ell_i = M$.

Then \mathfrak{M}_0 is isomorphic to $\overline{\mathcal{O}_\ell} \cap \mathcal{T}_m$, where

- \mathcal{O}_ℓ is the $GL(M)$ -orbit of nilpotent $M \times M$ matrices of Jordan type ℓ , i.e., with Jordan blocks of size ℓ_i , $i = 1, \dots, N$.
- $\mathcal{T}_m = x_m + \mathcal{T}'_m$,
 - x_m is a nilpotent operator of Jordan type m , which we shall choose to be in Jordan form, i.e., x_m is block diagonal with blocks $\pi_1 = [1, m_1]$, $\pi_2 = [m_1 + 1, m_1 + m_2]$, \dots , $\pi_N = [M - m_N + 1, M]$ and 1's right above the diagonal in each diagonal block.
 - \mathcal{T}'_m is a certain linear subspace defined as follows: in each block $\pi_i \times \pi_j$ (with the same decomposition of rows and columns into intervals as above), the only nonzero entries are on the last row and $\min(m_i, m_j)$ leftmost columns.

An important property of the intersection of $\overline{\mathcal{O}_\ell}$ and \mathcal{T}_m is that it's *transverse*, see [14] for details.

2.4. Tensor product quiver varieties. Suppose the direct sum $W := \bigoplus_{a=1}^{k-1} W_a$ is given an (ordered) basis (e_1, \dots, e_N) , such that $e_i \in W_{m_i}$ for some $m \in \{1, \dots, k-1\}^N$ with $\#\{i : m_i = a\} = w_a$. Note that the latter condition characterizes precisely the sequences (m_1, \dots, m_N) of the previous section.

This provides an isomorphism between $\mathfrak{gl}(W)$ (resp. $GL(W)$) and $\mathfrak{gl}(N)$ (resp. $GL(N)$), as well as a Borel subgroup, with its unipotent subgroup, Cartan torus and their Lie algebras. Explicitly, via the isomorphisms above, we define:

$$\begin{aligned} \mathfrak{n} &= \{\text{strict upper triangular matrices}\} \subset \mathfrak{gl}(W) \\ T &= \{\text{invertible diagonal matrices}\} \subset GL(W) \end{aligned}$$

Note that in fact, $T \subset \prod_{a=1}^{k-1} GL(W_a)$, so it acts in the natural way: $g \in T : (B_a, i_a, j_a) \mapsto (B_a, i_a g^{-1}, g j_a)$, and since this action commutes with that of G_v , acts on \mathfrak{M}_0 (or \mathfrak{M}).

Consider the particular one parameter subgroup $g(t) = \text{diag}(t^{-i}, i = 1, \dots, N) \in T$, $t \in \mathbb{C}^\times$. Then define

$$\mathfrak{Z}_0 = \{x \in \mathfrak{M}_0 : g(t)x \xrightarrow{t \rightarrow 0} 0\}$$

²This hypothesis can be easily dispensed with by replacing in what follows $\mathfrak{M}_0(v, w)$ with the image of p .

At one point, we shall also need to consider $\mathfrak{Z} := p^{-1}(\mathfrak{Z}_0)$.

Using the alternative description of sect. 2.3, we can reexpress \mathfrak{Z}_0 as follows. First embed $\mathfrak{gl}(N)$ inside $\mathfrak{gl}(M)$ as matrices that are proportional to the identity inside each block $\pi_i \times \pi_j$ corresponding to the Jordan decomposition of x_m . Then via this embedding, we simply have

$$\mathfrak{Z}_0 = \mathfrak{M}_0 \cap \mathfrak{n}$$

The affine scheme \mathfrak{Z}_0 is typically reducible, and equidimensional of dimension $\frac{1}{2} \dim \mathfrak{M}_0$ (this is of course related to an underlying Lagrangianity, which we do not discuss here). We denote $\mathfrak{Z}_{0,\alpha}$ its irreducible components, where α runs over some indexing set, which can be chosen as follows. It consists of the set of tableaux of shape λ with the following restrictions:

- The letter i is used m_i times, $i = 1, \dots, N$.
- Rows are strictly increasing; columns are weakly increasing (i.e., it is the conjugate of a semi-standard Young tableau).

This labelling can be obtained using a generalization of Spaltenstein's algorithm [22], which consists in taking a generic element X of $\mathfrak{Z}_{0,\alpha}$ viewed as a $M \times M$ matrix and computing the Jordan forms of upper-left submatrices $(X_{ij})_{1 \leq i, j \leq m_1 + \dots + m_h}$, $h = 1, \dots, N$; the corresponding increasing sequence of partitions forms the tableau α .

Similarly, one can introduce $\mathfrak{Z} = p^{-1}(\mathfrak{Z}_0)$. Its irreducible components \mathfrak{Z}_α can be indexed as follows: α is a collection of subsets α_i of $\{1, \dots, k\}$, $i = 1, \dots, N$, such that $\#\alpha_i = m_i$ and $\#\{i : a \in \alpha_i\} = \lambda_a$, $a = 1, \dots, k$ (where the λ_a are the lengths of rows of λ viewed as a box diagram). Then the map φ from $\text{Irr}(\mathfrak{Z}_0)$ to $\text{Irr}(\mathfrak{Z})$ corresponding to taking p^{-1} is to associate to a tableau T the sequence $\alpha_i = \{\text{rows where } i \text{ is in } T\}$. This map is in general not surjective.

2.5. Multidegrees. As noted above, the torus $T \cong (\mathbb{C}^\times)^N$ acts on \mathfrak{M}_0 . Furthermore, an extra \mathbb{C}^\times action can be introduced as follows. In the original definition of \mathfrak{M}_0 , it simply scales every linear map: $\mathbb{C}^\times \ni t : (B_{a,a+1}, B_{a+1,a}, i_a, j_a) \mapsto (tB_{a,a+1}, tB_{a+1,a}, ti_a, tj_a)$. In the picture of sect. 2.3, it acts on the slice \mathcal{T}_m by scaling the entry on the last row of each block $\pi_i \times \pi_j$ with $t^{\text{perimeter} - 2(\text{column} - 1)}$, where the perimeter is $m_i + m_j$, and the column goes from 1 to $\min(m_i, m_j)$.

It is not hard to check that $T \times \mathbb{C}^\times$ leaves \mathfrak{Z}_0 , and therefore its components $\mathfrak{Z}_{0,\alpha}$, invariant. We want to consider their *equivariant volumes* with a particular polynomial normalization. Recall that from sect. 2.3 we have an embedding, which we denote ι , from $\mathfrak{Z}_0 = \mathfrak{M}_0 \cap \mathfrak{n}$ to $\mathcal{T}_m \cap \mathfrak{n}$. We can then consider pushforward in $(T \times \mathbb{C}^\times)$ -equivariant cohomology:

$$\Psi_\alpha := \iota_*[\mathfrak{Z}_{0,\alpha}] \in H_{T \times \mathbb{C}^\times}^*(\mathcal{T}_m \cap \mathfrak{n})$$

Since $\mathcal{T}_m \cap \mathfrak{n}$ is equivariantly contractible, its equivariant cohomology is that of a point, i.e., a polynomial ring. We write it as

$$H_{T \times \mathbb{C}^\times}^*(\mathcal{T}_m \cap \mathfrak{n}) = \mathbb{Z}[z_1, \dots, z_N, \hbar/2]$$

where each z_i is the coordinate on $\mathfrak{t} := \text{Lie}(T)$ corresponding to the basis element e_i , and $\hbar/2$ corresponds to the extra \mathbb{C}^\times action.³ The Ψ_α are sometimes called the *multidegrees* of the $\mathfrak{Z}_{0,\alpha}$ in $\mathcal{T}_m \cap \mathfrak{n}$. They are homogeneous polynomials of degree, the codimension of \mathfrak{Z}_0 in $\mathcal{T}_m \cap \mathfrak{n}$. The latter is independent of m (this will be a consequence of transversality, see

³The factor $1/2$ in the generator $\hbar/2$ is there to match the conventions of integrable system. In fact, one should further perform the substitution $\hbar \rightarrow -\hbar$ for an exact match; but that would obscure the notion of positivity coming from geometry.

sect. 3.2.2), and is given by $\text{codim } \mathfrak{Z}_0 = \sum_{a=1}^k \frac{\lambda_a(\lambda_a-1)}{2}$ (where the λ_a are the lengths of the rows of the box diagram of λ).

2.6. Representation-theoretic interpretation. Denote by L_α the irreducible representation of $SL(k)$ with highest weight α . It is known that there is a natural isomorphism between the top Borel–Moore homology of \mathfrak{Z}_0 and $\text{Hom}_{SL(k)}(L_\lambda, L_{\omega_{m_1}} \otimes L_{\omega_{m_2}} \otimes \cdots \otimes L_{\omega_{m_N}})$. In particular the number of irreducible components of \mathfrak{Z}_0 is equal to the multiplicity of L_λ in $L_{\omega_{m_1}} \otimes L_{\omega_{m_2}} \otimes \cdots \otimes L_{\omega_{m_N}}$.

We can therefore reinterpret $\Psi := \iota_*$ as an element of $\mathcal{H} \otimes \mathbb{Z}[z_1, \dots, z_N, \hbar/2]$ where

$$\mathcal{H} := (L_{\omega_{m_1}}^* \otimes L_{\omega_{m_2}}^* \otimes \cdots \otimes L_{\omega_{m_N}}^* \otimes L_\lambda)^{SL(k)}$$

More explicitly, $\Psi = \sum_\alpha \Psi_\alpha u^\alpha$ where the u^α form the basis dual to the $[\mathfrak{Z}_{0,\alpha}]$.

3. VERTEX OPERATORS AND QUANTUM KNIZHNIK–ZAMOLODCHIKOV EQUATION

In the previous section, given a quiver variety and a basis (e_1, \dots, e_N) of $W = \bigoplus_{a=1}^{k-1} W_a$, we have defined geometrically a set of polynomials Ψ_α which we have grouped into a polynomial-valued vector $\Psi \in \mathcal{H} \otimes \mathbb{Z}[z_1, \dots, z_N, \hbar/2]$. We now study properties of these polynomials.

We shall emphasize the dependence of our construction on the choice of basis (e_1, \dots, e_N) as follows. We shall denote when required $\mathfrak{Z}_0 := \mathfrak{Z}_0^{e_1, \dots, e_N}$, and similarly for other geometric objects. Note however that Ψ only depends on the e_i via the combinatorial data of the m_i (such that $e_i \in W_{m_i}$); indeed given two bases with the same m_i , there is an obvious isomorphism from each W_a to itself which is equivariant w.r.t. the corresponding two tori, and so the equivariant classes of the $\mathfrak{Z}_{0,\alpha}$ viewed as elements of $\mathbb{Z}[z_1, \dots, z_N, \hbar/2]$ are the same. We therefore denote

$$\Psi = \Psi^{m_1, \dots, m_N}, \quad \mathcal{H} = \mathcal{H}^{m_1, \dots, m_N}$$

3.1. Exchange relation. The first important relation that Ψ satisfies is the so-called exchange relation. As we shall see, it is a set of relations involving not a single Ψ^{m_1, \dots, m_N} (unless the m_i 's are all equal), but rather all permutations of the sequence of m_i 's. This section is closely related to [13, chapter 4] in the sense that what is called here exchange relation is essentially the *definition* of the R -matrix there, with some subtleties, as we shall see in the proof of the following

Proposition 1. *There exist $\check{R}_i(z) \in \text{Hom}(\mathcal{H}^{m_1, \dots, m_i, m_{i+1}, \dots, m_N}, \mathcal{H}^{m_1, \dots, m_{i+1}, m_i, \dots, m_N}) \otimes \mathbb{Q}(z, \hbar)$, $i = 1, \dots, N-1$, which satisfy*

$$\begin{aligned} (1) \quad & \check{R}_i(u) \check{R}_{i+1}(u+v) \check{R}_i(v) = \check{R}_{i+1}(v) \check{R}_i(u+v) \check{R}_{i+1}(u) & i = 1, \dots, N-2 \\ (2) \quad & \check{R}_i(u) \check{R}_i(-u) = 1 & i = 1, \dots, N-1 \\ (3) \quad & \check{R}_i(u) \check{R}_j(v) = \check{R}_i(v) \check{R}_j(u) & |i-j| > 1 \end{aligned}$$

such that

$$\begin{aligned} (4) \quad & \Psi^{m_1, \dots, m_{i+1}, m_i, \dots, m_N}(z_1, \dots, z_{i+1}, z_i, \dots, z_N) \\ &= \check{R}_i(z_i - z_{i+1}) \Psi^{m_1, \dots, m_i, m_{i+1}, \dots, m_N}(z_1, \dots, z_i, z_{i+1}, \dots, z_N), \quad i = 1, \dots, N-1. \end{aligned}$$

Note that $\check{R}_i(z)$ is a rational function of both z and \hbar , but it is traditional in integrable systems to emphasize in the notation the dependence on z .

We explain here the main steps of the proof:

- The first basic idea is to compare the various $\mathfrak{Z}^{e_1, \dots, e_N}$ when one permutes the e_i (the appearance of the symmetric group \mathcal{S}_N is related to the “gauge group” $\prod_a GL(W_a)$ being of type A). The classes of the irreducible components $\mathfrak{Z}_\alpha^{e_1, \dots, e_N}$ are known to form a basis of the (appropriately localized) equivariant cohomology ring of \mathfrak{M} . Since permutations of the e_i ’s do not affect the torus T , we have at our disposal $N!$ different bases of $H_{T \times \mathbb{C}^*}^{*, loc}(\mathfrak{M})$ as free modules over $H_{T \times \mathbb{C}^*}^{*, loc}(\cdot)$. We may as well consider elementary transpositions only, and then write formally

$$[\mathfrak{Z}_\alpha^{\dots e_{i+1}, e_i \dots}] = \sum_{\beta} (\check{\mathfrak{R}}_i)_\alpha^\beta [\mathfrak{Z}_\beta^{\dots e_i, e_{i+1} \dots}]$$

where the $\check{\mathfrak{R}}_i)_\alpha^\beta$ are matrices in $H_{T \times \mathbb{C}^*}^{*, loc}(\cdot)$. This analysis is not entirely satisfactory, and we mention briefly how it can be improved (this will not be necessary for the statement of any of the theorems in this paper, but is definitely needed to prove them).

One can perform on the basis of the $[\mathfrak{Z}_\alpha]$ any further linear transformation that is compatible with the \mathcal{S}_N action. A good choice is to switch to the “stable” basis, which we shall not define here (see [13] and app. A), and which corresponds to a change from the $[\mathfrak{Z}_\alpha]$ to the say $[\mathfrak{Z}'_\alpha] = \sum_{\beta} c_\alpha^\beta [\mathfrak{Z}_\beta]$. The coefficients c_α^β of the change of the basis are upper triangular (w.r.t. to a natural order on the indexing set), and \mathbb{Z} -valued; and the R -matrices in this new basis, defined by $[\mathfrak{Z}'_\alpha]^{\dots e_{i+1}, e_i \dots} = \sum_{\beta} (\check{\mathfrak{R}}'_i)_\alpha^\beta [\mathfrak{Z}'_\beta]^{\dots e_i, e_{i+1} \dots}]$, have various nice properties which are explained in [13]. In particular, they have a “locality” property w.r.t. tensor product. One practical consequence is that the matrix entries of $\check{\mathfrak{R}}'_i$ (and therefore of $\check{\mathfrak{R}}_i$), as elements of $\mathbb{Q}(z_1, \dots, z_N, \hbar/2)$, are functions of $z_i - z_{i+1}$ and \hbar only.

- Next we want to pushforward from \mathfrak{M} to \mathfrak{M}_0 using p_* . Since \mathfrak{Z} and \mathfrak{Z}_0 are equidimensional of same dimension, given a component \mathfrak{Z}_α of \mathfrak{Z} , if one applies p one of two things may happen: either it is sent to something lower-dimensional, or it is sent to an irreducible component of \mathfrak{Z}_0 , which is nothing but $\mathfrak{Z}_{0, \alpha}$ if we identify a tableau α with its image under φ (see sect. 2.4); in which case the map turns out to be generically one-to-one. This means that in equivariant cohomology, $[\mathfrak{Z}_\alpha]$ is sent to either zero or $[\mathfrak{Z}_{0, \alpha}]$. In the end, we get the exact same equality

$$(5) \quad [\mathfrak{Z}_{0, \alpha}^{\dots e_{i+1}, e_i \dots}] = \sum_{\beta} (\check{\mathfrak{R}}_i)_\alpha^\beta [\mathfrak{Z}_{0, \beta}^{\dots e_i, e_{i+1} \dots}]$$

where the range of indices has been appropriately restricted.

- Finally we want to compute equivariant volumes, with a prescribed normalization dictated by the embedding space. Two complications need to be addressed at this stage:
 - In order to turn equality (5) into an equality of polynomials, one has to parameterize the torus. Here we break the symmetry between $\dots e_i, e_{i+1} \dots$ and $\dots e_{i+1}, e_i \dots$ by stating that z_i is the coordinate corresponding to e_i . If we then apply ι_* to both sides of (5), the r.h.s. behaves as expected: $\check{\mathfrak{R}}_i$ becomes a $\mathbb{Q}(z_1, \dots, z_N, \hbar/2)$ -valued matrix, and is fact as already mentioned is $\mathbb{Q}(z_i - z_{i+1}, \hbar)$ -valued (one can be even more precise since the localization only allows denominators of the form of a product of $a\hbar + z_i - z_{i+1}$, $a \in \mathbb{Z}$); and $[\mathfrak{Z}_{0, \beta}^{\dots e_i, e_{i+1} \dots}]$ becomes $\Psi_\beta^{\dots m_i, m_{i+1} \dots}$. However the l.h.s. is not exactly $\Psi_\alpha^{\dots m_{i+1}, m_i \dots}$ as one might naively expect because of the mismatch in the parameterization of the torus: one needs to exchange variables z_i and z_{i+1} to take it into account.

- The embedding spaces for $\mathfrak{Z}_0^{\dots e_i, e_{i+1} \dots}$ and $\mathfrak{Z}_0^{\dots e_{i+1}, e_i \dots}$ are not the same: this means when we pass from (5) to equivariant volumes, one needs to introduce a corrective factor corresponding to the ratio of equivariant volumes of $\mathcal{T}_{\dots m_i, m_{i+1} \dots} \cap \mathfrak{n}$ and $\mathcal{T}_{\dots m_{i+1}, m_i \dots} \cap \mathfrak{n}$. The latter can in fact be computed explicitly and is

$$\prod_{a=1}^{\min(m_i, m_{i+1})} \frac{a\hbar - z_i + z_{i+1}}{a\hbar - z_{i+1} + z_i}$$

In order to accommodate for this corrective factor, we introduce a new normalization of the R -matrix:

$$(6) \quad \check{R}_i(z) := \prod_{a=1}^{\min(m_i, m_{i+1})} \frac{a\hbar - z}{a\hbar + z} \check{\mathfrak{R}}_i(z)$$

(this is a rather minor issue but is important to compare explicitly the results of [2, 21] and of app. A to those of [13]).

Putting everything together, we find that Eq. (4) is precisely satisfied.

- Successive changes of basis should lead to the relations of the symmetric group \mathcal{S}_N for the operators $\check{\mathfrak{R}}_i$. However, as explained in the previous paragraph, one must take into account the possible reparameterization of the torus due to permutation of the e_i . In other words, after a first change of basis leading to $\check{\mathfrak{R}}_i$, the next change of basis corresponding to elementary transposition $(j, j+1)$ will not be given by $\check{\mathfrak{R}}_j$ but rather by $\tau_i \check{\mathfrak{R}}_j$, where τ_i is the operator on $\mathbb{Q}(z_1, \dots, z_N, \hbar/2)$ that permutes z_i and z_{i+1} . More generally, viewing the $(\check{\mathfrak{R}}_i)_\alpha^\beta$ as operators of multiplication on $\mathbb{Q}(z_1, \dots, z_N, \hbar/2)$, the precise statement is that the $\tau_i \check{\mathfrak{R}}_i$ satisfy the symmetric group relations. Rewriting these explicitly by pulling out the τ_i (and using the fact that the τ_i alone satisfy the same relations) results in Eqs. (1–3) first for the $\check{\mathfrak{R}}_i$, then, noting that transformation (6) preserves them, for the \check{R}_i .

Given the polynomials Ψ , it is not hard to see that (4) defines uniquely the \check{R}_i for $N \geq 3$. So (4) can in principle be considered as a (somewhat clumsy) definition of the R -matrix, and it is in that sense that it is equivalent (for $N \geq 3$) to the definition of [13].

3.2. Correlators of Yangian Vertex Operators. The exchange relation (4) does not characterize the polynomial-valued vectors Ψ uniquely. We now give a formula for them which does (up to normalization).

We start from the centrally extended double of the Yangian of $\mathfrak{sl}(k)$, which we denote $\widehat{DY(\mathfrak{sl}(k))}$. It was introduced in [8] and the case $k = 2$ was studied further in [9]. One should think of it as a “rational” analogue (in the sense of the classification of the solutions of the Yang–Baxter equation) of the “trigonometric” quantized affine algebras, and its representation theory is expected to run parallel to that of the latter, though some facts that we present now have not been derived rigorously in the literature, as far as this author knows.

The value of the central element in an irreducible representation of $\widehat{DY(\mathfrak{sl}(k))}$ is called the *level*. We are here interested in two types of modules of $\widehat{DY(\mathfrak{sl}(k))}$:

- Evaluation modules $L_\nu(z)$, where z is a formal parameter, which are level 0 and isomorphic to $L_\nu \otimes \mathbb{C}[z, z^{-1}]$ as $U(\mathfrak{sl}(k))$ -modules.

- Highest weight modules $\mathcal{V}_{1,\lambda}$, where we separated the highest weight of $\widehat{\mathfrak{sl}(k)}$ into the level, which for us will always be 1, and the highest weight λ of the finite-dimensional algebra $\mathfrak{sl}(k)$; in fact in level 1, λ can only be zero (case of the so-called basic representation) or a fundamental weight.

Next we define type I (dual) vertex operators (VOs) $\Phi_{\omega_a}(z)$, $a = 1, \dots, k-1$, i.e., intertwiners

$$\Phi_{\omega_a}^{1,\lambda,\lambda'}(z) : \mathcal{V}_{1,\lambda} \otimes L_{\omega_a}(z) \rightarrow \mathcal{V}_{1,\lambda'}$$

They are unique up to multiplication by a scalar, and the exact choice of normalization is irrelevant for our purposes. Furthermore, they are “perfect” VOs in the sense that λ' is entirely determined by λ and ω_i . Explicitly, if $\lambda = \omega_b$, $b = 0, \dots, k-1$ (with $\omega_0 := 0$), then $\lambda' = \omega_{b+a \pmod{k}}$. Because of this fact one can safely suppress the superscripts and write simply $\Phi_{\omega_a}(z)$.

An important ingredient is the bosonic realization of the level 1 representations. This construction is performed in [8, 9] for $k = 2$ and can be extended straightforwardly to any k . It consists of a $DY(\widehat{\mathfrak{sl}(k)})$ -module \mathcal{B} which is a bosonic Fock space, that is the direct sum of copies of the highest weight module of $\widehat{\mathfrak{gl}(1)^{k-1}}$, the Heisenberg algebra sitting inside $DY(\widehat{\mathfrak{sl}(k)})$. The highest weight vectors are denoted $|\lambda\rangle$, where λ runs over the weight lattice of $\mathfrak{sl}(k)$. In particular if λ is zero or a fundamental weight, $|\lambda\rangle$ is a highest weight vector of the whole of $DY(\widehat{\mathfrak{sl}(k)})$, with associated submodule $\mathcal{V}_{1,\lambda}$.

The dual module \mathcal{B}^* is similarly a direct sum of lowest weight modules, and we denote the lowest weight vectors $\langle\lambda|$.

One more notation is needed: a highest weight vector $|\lambda\rangle$ of $\widehat{\mathfrak{gl}(1)^{k-1}}$, where λ is dominant, generates a submodule of the finite-dimensional algebra $\mathfrak{sl}(k)$ which is isomorphic to L_λ . This defines a unique (up to normalization) vector of $L_\lambda^* \otimes \mathcal{B}$ which we denote $|L_\lambda^*\rangle$. Below we need $|L_\lambda\rangle$ rather than $|L_\lambda^*\rangle$; note that $L_\lambda^* \cong L_{\lambda^*}$ where by definition $\lambda^* := -w_0\lambda$, w_0 longest permutation in \mathcal{S}_k .

We can then state:

Theorem 1. *The following formula holds:*

$$(7) \quad \Psi(z_1, \dots, z_N) = \frac{1}{\kappa(z_1, \dots, z_N)} \langle 0 | \Phi_{\omega_{m_1}}(z_1) \dots \Phi_{\omega_{m_N}}(z_N) | L_\lambda \rangle$$

where $\kappa(z_1, \dots, z_N)$ is a meromorphic scalar function.

Note that the product of VOs in this expression is the product as linear operators on \mathcal{B} . All together, the r.h.s. of (7) is an element of $L_{\omega_{m_1}}^* \otimes L_{\omega_{m_2}}^* \otimes \dots \otimes L_{\omega_{m_N}}^* \otimes L_\lambda$, as should be (and in fact the intertwining property of the VOs for $\mathfrak{sl}(k)$ ensures that it lies more precisely in the $\mathfrak{sl}(k)$ -invariant subspace, just like the l.h.s., cf sect. 2.6).

This can be considered the main result of this paper. In the next paragraphs we provide a sketch of proof of it. It proceeds in two steps: first we prove it in the case $\mu = N\omega_1$; then we extend it to the general case by using the fusion procedure. Note that contrary to the exchange relation, we do not know of a geometric proof.

3.2.1. Case of $\mu = N\omega_1$: orbital varieties. If $\mu = N\omega_1$, $\mathfrak{Z}_0 = \overline{\mathcal{O}_\ell} \cap \mathfrak{n}$ is known as the orbital scheme associated to the nilpotent orbit closure $\mathfrak{M}_0 = \overline{\mathcal{O}_\ell}$, and its irreducible components $\mathfrak{Z}_{0,\alpha}$ are called *orbital varieties* (and \mathfrak{M} is the cotangent bundle of an appropriate partial flag variety). These were already studied in a similar context in [2, 21], although the formula of Thm. 1 in terms of Vertex Operators was not given there.

One of the main results of [21] is that Ψ satisfies the exchange relation (4), where the R -matrix was identified explicitly; it is given by

$$(8) \quad \check{R}_i(z) = \frac{\hbar - zP_{i,i+1}}{\hbar + z}$$

where $P_{i,i+1}$ permutes factors i and $i+1$ of the tensor product (there is an overall minus sign mismatch compared to [21], which is due to different conventions).

Now the level 1 VOs $\Phi(z) := \Phi_{\omega_1}(z)$ satisfy an exchange relation of their own:

$$(9) \quad \check{R}^*(z_1 - z_2)\Phi(z_1)\Phi(z_2) = \Phi(z_2)\Phi(z_1)$$

but with a different normalization of the R -matrix: [9]

$$\check{R}^*(z) = \frac{f(z)}{f(-z)}\check{R}(z), \quad f(z) = \frac{\Gamma(1 - \frac{z}{kh})}{\Gamma(1 - \frac{z-h}{kh})}$$

This implies that if one sets

$$(10) \quad \kappa(z_1, \dots, z_N) = \prod_{1 \leq i < j \leq N} f(z_j - z_i)$$

and defines as in Thm. 1

$$\Xi(z_1, \dots, z_N) = \frac{1}{\kappa(z_1, \dots, z_N)} \langle 0 | \Phi(z_1) \dots \Phi(z_N) | L_\lambda \rangle$$

then Ξ satisfies the exchange relation (4) (with the same normalization of the R -matrix as Ψ).

Furthermore, the explicit form (8) (identity plus permutation of indices) of the R -matrix shows that given one entry of Ψ in the standard basis of a weight space of $(\mathbb{C}^k)^{\otimes N}$ (which is identified in the present context with the stable basis), all other entries are determined uniquely by repeated application of the exchange relation (4). Explicitly, writing these entries as $\Psi'_\alpha = \sum_\beta c_\alpha^\beta \Psi_\beta$ and similarly for Ξ , if we can show that $\Psi'_\alpha = \Xi'_\alpha$ for some α , then $\Psi = \Xi$.

On the geometric side, consider the (standard) tableau $\alpha^{(0)}$ of shape λ obtained by filling boxes with $1, \dots, N$ row by row, e.g.,

1	2	3
4	5	
6		

$$\mathfrak{Z}_{0,\alpha^{(0)}} = \{U \text{ } N \times N \text{ upper triangular: } U_{ij} = 0 \text{ if } i \text{ and } j \text{ are on the same row of } \alpha^{(0)}\}$$

It is elementary to show that $\mathfrak{Z}_{0,\alpha^{(0)}}$ as defined above is an irreducible component of \mathfrak{Z}_0 (it sits in it and has maximal dimension), and indeed corresponds to the particular tableau $\alpha^{(0)}$. We have immediately

$$\Psi_{\alpha^{(0)}} = \prod_{\substack{1 \leq i < j \leq N \\ i \text{ and } j \text{ on same row of } \alpha^{(0)}}} (\hbar + z_i - z_j)$$

The tableau $\alpha^{(0)}$ is special in that it is the smallest w.r.t. the natural order on tableaux for which the change of basis to the stable basis is triangular; that means explicitly that $\Psi'_{\alpha^{(0)}} = \Psi_{\alpha^{(0)}}$ where as usual we identify $\alpha^{(0)}$ with its image under φ , namely $(\underbrace{1, \dots, 1}_{\lambda_1}, \dots, \underbrace{k, \dots, k}_{\lambda_k})$.

On the VO side, one can perform the calculation of the expectation value along the same lines as [10] (which only treats the $k = 2$ case). Alternatively, one can start from the

corresponding calculations for the quantized affine algebra $U_q(\widehat{\mathfrak{sl}(k)})$, as in [19, sect. 9], and take the limit $\epsilon \rightarrow 0$ with $q = e^{-\epsilon\hbar/2}$, $w = e^{\epsilon z}$ (where w stands here for any multiplicative spectral parameter).

We find that if $\alpha^{(0)}$ is any weakly increasing sequence, i.e., is of the form above: $\alpha^{(0)} = (\underbrace{1, \dots, 1}_{\lambda_1}, \dots, \underbrace{k, \dots, k}_{\lambda_k})$, then the following identity holds:

$$\langle 0 | \Phi(z_1)_{\alpha_1^{(0)}} \dots \Phi(z_N)_{\alpha_N^{(0)}} | \lambda^* \rangle = \prod_{1 \leq i < j \leq N} f(z_i - z_j) \prod_{\substack{1 \leq i < j \leq N \\ \alpha_i^{(0)} = \alpha_j^{(0)}}} (\hbar + z_i - z_j)$$

(where $\Phi(z)_a$, $a = 1, \dots, k$, denotes the entry of $\Phi(z)$ in the standard basis of \mathbb{C}^k).

Combining the various formulae above, we conclude that $\Psi'_{\alpha^{(0)}} = \Xi'_{\alpha^{(0)}}$, and therefore $\Psi = \Xi$.

3.2.2. Fusion procedure and transverse slice. We first explain the fusion procedure and how it allows us to reduce the computation of the r.h.s. of (7) to the case of the previous section, with $\mu = M\omega_1$.

Given a fundamental weight ω_a of $SL(k)$, $a = 1, \dots, k-1$, there is a (unique up to normalization) embedding p_a of L_{ω_a} into $L_{\omega_1}^{\otimes a}$ as $U(\mathfrak{sl}(k))$ -modules. Furthermore, the space $L_{\omega_1}(z - \frac{a-1}{2}\hbar) \otimes L_{\omega_1}(z - \frac{a-3}{2}\hbar) \otimes \dots \otimes L_{\omega_1}(z + \frac{a-1}{2}\hbar)$ is reducible for the whole $DY(\widehat{\mathfrak{sl}(k)})$ -action, and the image of p_a forms an invariant subspace which is isomorphic to $L_{\omega_a}(z)$. (noting again that the usual integrable systems sign convention corresponds to $\hbar \rightarrow -\hbar$).

Consider then the operator

$$(11) \quad \Phi(z - \frac{a-1}{2}\hbar) \Phi(z - \frac{a-3}{2}\hbar) \dots \Phi(z + \frac{a-1}{2}\hbar) p_a$$

It is by definition an intertwiner, and we conclude that it is equal to $\Phi_{\omega_a}(z)$ up to normalization, by uniqueness of this intertwiner. Therefore the r.h.s. of (7) is nothing but

$$(12) \quad \frac{1}{\kappa'(z_1, \dots, z_N)} \langle 0 | \Phi(z_1 - \frac{m_1-1}{2}\hbar) \dots \Phi(z_1 + \frac{m_1-1}{2}\hbar) p_1 \dots \Phi(z_N - \frac{m_N-1}{2}\hbar) \dots \Phi(z_N + \frac{m_N-1}{2}\hbar) p_N | L_\lambda \rangle$$

where we absorbed normalization issues in the scalar function κ' , i.e., $\kappa'(z_1, \dots, z_N) = \kappa(z_1, \dots, z_N) \prod_{i=1}^N c_{m_i}(z_i)$ (we shall not need to compute the $c_a(z)$ explicitly). So the r.h.s. now looks like its special case where $\mu = M\omega_1$.

Now let us consider the l.h.s. of (7). We shall finally use the construction of sect. 2.3. Recall that $\mathfrak{M}_0 = \overline{\mathcal{O}_\ell} \cap \mathcal{T}_m$, where we reinterpret in the present context $\mathfrak{M}_0^{(1)} := \overline{\mathcal{O}_\ell}$ as the singular Nakajima variety associated to $\mu = M\omega_1$ and same λ . Similarly, $\mathfrak{Z}_0 = \mathfrak{Z}_0^{(1)} \cap \mathcal{T}_m$, where $\mathfrak{Z}_0^{(1)} := \overline{\mathcal{O}_\ell} \cap \mathfrak{n}$ is the tensor product quiver variety for $\mu = M\omega_1$, i.e., $m = \underbrace{(1, \dots, 1)}_M$.

A nice property of the Mirkovic–Vybornov slice is that it is still transverse on $\mathfrak{Z}_0^{(1)}$. More specifically, given an irreducible component $\mathfrak{Z}_{0,\alpha}^{(1)}$, the intersection is either empty, or transverse and irreducible (irreducibility is in fact also a corollary of the argument that follows).

Now let us compute multidegrees. The $\mathfrak{Z}_{0,\alpha}^{(1)}$ are invariant under a torus $T^{(1)} \cong (\mathbb{C}^\times)^M \times \mathbb{C}^\times$, but the slice with \mathcal{T}_m only preserves a subtorus $T \subset T^{(1)}$, with $T \cong (\mathbb{C}^\times)^M \times \mathbb{C}^\times$. The subtorus $(\mathbb{C}^\times)^M$ is easy to understand: in accordance with sect. 2.4, it corresponds to conjugation

w.r.t. invertible diagonal matrices which are proportional to the identity in each Jordan block of x_m . The extra \mathbb{C}^\times is more subtle; an explicit formula was given at the beginning of sect. 2.5. We recover it now as follows.

Any element of \mathcal{T}_m , just like x_m itself, has a 1 right above the diagonal in each Jordan block. In order for T to preserve \mathcal{T}_m , the weight of those entries w.r.t. T must be zero. Now the weights of $\mathfrak{gl}(M)$ w.r.t. $T^{(1)}$ are simply $\hbar + z_i^{(1)} - z_j^{(1)}$, $i, j = 1, \dots, M$, (where we added the superscripts (1) for convenience), each one corresponding to the entry at (i, j) . We conclude that \mathfrak{t}^* , viewed as a quotient of $\mathfrak{t}^{(1)*}$, is generated by $z_1^{(1)}, \dots, z_M^{(1)}, \hbar$ with relations

$$\hbar + z_i^{(1)} - z_{i+1}^{(1)} = 0, \quad i, i+1 \in \pi_h, \quad h = 1, \dots, N$$

Note that the \mathbb{C}^\times itself viewed as a subgroup of T is not canonically defined and that corresponds to the freedom in solving the equations above as $z_i^{(1)} = z_h + cst + i\hbar$, $i \in \pi_h$, to shift z_h by a constant. We choose, as in sect. 2.5, to fix the constant by asking that the average of $z_i^{(1)}$ in each π_h be z_h .

We finally conclude that

$$(13) \quad [\mathfrak{Z}_{0,\alpha}^{(1)}]_T = \Psi_\alpha^{(1)}(z_1 - \frac{m_1-1}{2}\hbar, \dots, z_1 + \frac{m_1-1}{2}\hbar, \dots, z_N - \frac{m_N-1}{2}\hbar, \dots, z_N + \frac{m_N-1}{2}\hbar)$$

where the l.h.s. is the multidegree w.r.t. T , whereas $\Psi_\alpha^{(1)}(z_1, \dots, z_M)$ is by definition the multidegree w.r.t. $T^{(1)}$.

Now transversality of the intersection means that the multidegree of $\mathfrak{Z}_{\alpha,0}^{(1)}$ in \mathfrak{n} is equal to the multidegree of $\mathfrak{Z}_{0,\alpha}^{(1)} \cap \mathcal{T}_m$ in $\mathfrak{n} \cap \mathcal{T}_m$. We conclude that the l.h.s. of (13) is nothing but $\sum_\beta x_{\alpha,\beta} \Psi_\beta$, where $x_{\alpha,\beta}$ is the multiplicity of $\mathfrak{Z}_{0,\beta}$ in $\mathfrak{Z}_{0,\alpha}^{(1)} \cap \mathcal{T}_m$.

A more detailed analysis, which we shall skip here, shows that the stable basis can be identified with the standard basis of (the weight space of) $L_{\omega_{m_1}} \otimes \dots \otimes L_{\omega_{m_N}}$ (note that this is essentially forced on us by the locality of the basis w.r.t. tensor product and the fact that it respects weight space decomposition). This effectively fixes the matrix $x_{\alpha,\beta}$, and implies that

$$(14) \quad \Psi(z_1, \dots, z_N) = \Psi^{(1)}(z_1 - \frac{m_1-1}{2}\hbar, \dots, z_1 + \frac{m_1-1}{2}\hbar, \dots, z_N - \frac{m_N-1}{2}\hbar, \dots, z_N + \frac{m_N-1}{2}\hbar)(p_1 \otimes \dots \otimes p_N)$$

Comparing this with (12), and using (7) for $\mu = M\omega_1$, we fix $\kappa'(z_1, \dots, z_N) := \kappa(z_1 - \frac{m_1-1}{2}\hbar, \dots, z_1 + \frac{m_1-1}{2}\hbar, \dots, z_N - \frac{m_N-1}{2}\hbar, \dots, z_N + \frac{m_N-1}{2}\hbar)$ with κ given by (10), and obtain (7) in the general case.

As a final remark, the vertex operators $\Phi_{\omega_i}(z)$ satisfy an exchange relation as well:

$$\check{R}_{\omega_a, \omega_b}^*(z_1 - z_2) \Phi_{\omega_a}(z_1) \Phi_{\omega_b}(z_2) = \Phi_{\omega_b}(z_2) \Phi_{\omega_a}(z_1)$$

where from the fusion construction (cf (9) and (11)), $\check{R}_{\omega_a, \omega_b}^*(z)$ is up to normalization a product of $ab \check{R}^*$ matrices. This identifies the geometrically defined R -matrices of Prop. 1 with the R -matrices of $\widehat{DY}(\mathfrak{sl}(k))$ in the tensor product of two evaluation modules corresponding to fundamental representations, as expected (as usual, up to a scalar factor).

3.2.3. Recurrence relations and wheel conditions. As an aside, we can apply the same strategy as in the previous section to investigate the following question: what happens when in the construction of \mathfrak{M}_0 as a transverse slice, as in sect. 2.3, we use another lift of μ from $SL(k)$ to $GL(k)$, adding extra columns of length k ? That is, we write $\tilde{m} =$

$(m_1, \dots, m_{p-1}, k, m_p, \dots, m_N)$ and similarly $\tilde{\ell} = (k, \ell_1, \dots, \ell_N)$ (recall that the ordering of $\tilde{\ell}$ does not matter).

It is not hard to see that in $\overline{\mathcal{O}_{\tilde{\ell}}} \cap \mathcal{T}_{\tilde{m}}$, the k rows and columns of the $M \times M$ matrix corresponding to the block of size k in $x_{\tilde{m}}$ are completely fixed, i.e., the diagonal block is of Jordan form and the rest is zero. This provides a direct isomorphism $\overline{\mathcal{O}_{\tilde{\ell}}} \cap \mathcal{T}_{\tilde{m}} \cong \overline{\mathcal{O}_{\ell}} \cap \mathcal{T}_m = \mathfrak{M}_0$, and similarly for the tensor product variety, $\overline{\mathcal{O}_{\tilde{\ell}}} \cap \mathcal{T}_{\tilde{m}} \cap \tilde{\mathfrak{n}} \cong \overline{\mathcal{O}_{\ell}} \cap \mathcal{T}_m \cap \mathfrak{n} = \mathfrak{Z}_0$. Such isomorphisms of varieties in different sizes lead to *recurrence relations* for Ψ . As a first step, denote $\Psi_{\tilde{\alpha}}^{\tilde{m}}$ the multidegrees of the irreducible components of $\overline{\mathcal{O}_{\tilde{\ell}}} \cap \mathcal{T}_{\tilde{m}} \cap \tilde{\mathfrak{n}}$, which are naturally indexed by tableaux of $\tilde{\lambda}$ (the box diagram associated to $\tilde{\ell}$). Then from the above,

$$\Psi_{\tilde{\alpha}}^{\tilde{m}}(z_1, \dots, z_{p-1}, \zeta, z_p, \dots, z_N) = \prod_{i=1}^{p-1} \prod_{a=0}^{m_i-1} \left(\left(\frac{m_i + k}{2} - a \right) \hbar + z_i - \zeta \right) \prod_{i=p}^N \prod_{a=0}^{m_i-1} \left(\left(\frac{m_i + k}{2} - a \right) \hbar + \zeta - z_i \right) \Psi_{\alpha}^m(z_1, \dots, z_N)$$

where the nilpotent orbit is $\tilde{\ell}$ in the l.h.s., ℓ in the r.h.s., and the linear factors take care of the difference of embedding spaces. The tableau α is obtained from $\tilde{\alpha}$ by removing the boxes labelled p and then renumbering $i \mapsto i - 1$ for $i > p$.

One can then view the slice with \tilde{m} as a further slice of the one with the sequence $(m_1, \dots, m_{p-1}, n_1, \dots, n_r, m_p, \dots, m_N)$ with $n_1 + \dots + n_r = k$, and where now the $n_i < k$. Comparing the multidegrees leads to an actual recurrence relation between Ψ 's as defined in sect. 2:

$$(15) \quad \Psi_{\tilde{\alpha}}^{m_1, \dots, n_1, \dots, n_r, \dots, m_N}(z_1, \dots, z_{p-1}, \zeta_1, \dots, \zeta_r, z_p, \dots, z_N) \Big|_{\zeta_{i+1} - \zeta_i = \frac{n_i + n_{i+1}}{2} \hbar} \\ = \begin{cases} 0 & \text{if } \exists i < j \in \{p, p+1, \dots, p+r-1\}, \text{ row}(i) \geq \text{row}(j) \text{ in } \tilde{\alpha} \\ \prod_{i=1}^{p-1} \prod_{a=0}^{m_i-1} \left(\left(\frac{m_i + n_1}{2} - a \right) \hbar + z_i - \zeta_1 \right) \prod_{i=p}^N \prod_{a=0}^{m_i-1} \left(\left(\frac{m_i + n_r}{2} - a \right) \hbar + \zeta_r - z_i \right) & \text{otherwise} \end{cases} \quad n_1 + \dots + n_r = k$$

where once again α is obtained from $\tilde{\alpha}$ by removing boxes labelled $p, \dots, p+r-1$ and then shifting $i \mapsto i - r$ for $i \geq p+r$. (in the case $m_i = n_i = 1$, this recurrence relation was already mentioned in [2] but without any geometric proof.)

The reasoning can be pushed one step further. What about if we have an entry (strictly) greater than k in m , keeping ℓ of the usual form ($\ell_i \leq k$ for all i)? In that case we immediately find $\overline{\mathcal{O}_{\ell}} \cap \mathcal{T}_m = \emptyset$, and with the same argument, obtain

$$(16) \quad \Psi^{\dots, n_1, \dots, n_2, \dots, n_r, \dots}(\dots, \zeta_1, \dots, \zeta_2, \dots, \zeta_r, \dots) \Big|_{\zeta_{i+1} - \zeta_i = \frac{n_i + n_{i+1}}{2} \hbar} = 0, \quad n_1 + \dots + n_r > k$$

Here, in contradistinction with (15), the location of the ζ_i is arbitrary, as long as they are ordered. Equations (16) are known as *wheel conditions*.

3.3. Rational quantum Knizhnik–Zamolodchikov equation. We finally discuss an important special case for Ψ , which is when $|\lambda\rangle$ is a highest weight vector of $DY(\widehat{\mathfrak{sl}(k)})$. As already mentioned, this implies that λ is either zero or a fundamental weight of $SL(k)$; equivalently, it means that the box diagram of λ is either a rectangle of height k , or a “quasi-rectangle” (a rectangle with one extra partial column). Note that for a given w , there is a unique v such that λ satisfies these conditions.

In that case, it is expected that $\Psi(z_1, \dots, z_N)$ satisfies the rational quantum Knizhnik–Zamolodchikov equation (also known as difference KZ equation) [23], which can be considered as the rational limit of the (trigonometric) quantum Knizhnik–Zamolodchikov equation of

[3]. Note that this author has not found a prover derivation of this fact in the literature, though it should go along the same lines as the derivation of the usual q KZ equation for matrix elements of VOs of quantized affine algebras [3, 7].

The rational q KZ equation is a system of difference equations of the form

$$(17) \quad \Psi(z_1, \dots, z_i + s, \dots, z_N) = S_i(z_1, \dots, z_N) \Psi(z_1, \dots, z_i, \dots, z_N), \quad i = 1, \dots, N$$

where s is equal to the level plus the dual Coxeter number (in units of \hbar), so here $s = (k+1)\hbar$, and the S_i are certain linear operators which we do not need to describe explicitly.

Instead, one observes that using Eqs. (4) repeatedly (by say moving the argument $z_i + s$ to the rightmost position in the l.h.s. and moving the argument z_i to the leftmost position in the r.h.s.), one can render (17) equivalent to another equation which involves cyclic shift of the parameters z_i . More specifically, one finds the following cyclicity equation:

$$(18) \quad \Psi^{m_2, \dots, m_N, m_1}(z_2, \dots, z_N, z_1 + (k+1)\hbar) = \rho \Psi^{m_1, \dots, m_N}(z_1, \dots, z_N)$$

where the rotation operator ρ is a constant operator (i.e., with no dependence on the z_i) which implements cyclic rotation of factors of the tensor product in $L_{\omega_{m_1}}^* \otimes \dots \otimes L_{\omega_{m_N}}^*$. In the case $\lambda = 0$, it has an explicit combinatorial definition: $\rho_\alpha^\beta = \varepsilon^{m_1} \delta_\alpha^{\rho(\beta)}$, with $\varepsilon = (-1)^{\frac{M}{k}-1}$, and $\rho(\beta)$ is obtained from β by tableau *promotion* (evacuation of the m_1 letters “1” followed by cyclic shift of labels).

Note a technical difference between the system (4,18) on the one hand and (17) on the other hand: the former mixes the various $\Psi^{m_{\sigma(1)}, \dots, m_{\sigma(N)}}$, $\sigma \in \mathcal{S}_N$, whereas the latter involves a single Ψ^{m_1, \dots, m_N} .

4. CONCLUSION

In this short paper, we have expressed multidegrees of irreducible components of tensor product quiver varieties in terms of correlators of appropriate Yangian Vertex Operators. By means of bosonization this provides explicit formulae for them; also, various properties such as conformal block conditions (see [21]) can be easily derived. In a special case, we have shown that they are in fact (polynomial) solutions of the q KZ equation, though a full geometric proof is lacking. Indeed, only the exchange relation (the “nonaffine” part of q KZ, the whole of q KZ being related to an affine Weyl group action) was derived geometrically.

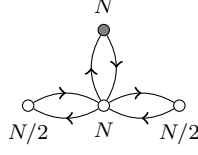
There are many possible generalizations of this work. In particular two underlying Dynkin diagrams can be generalized away from type A:

- The quiver itself, of course, can be chosen of type ADE, leading to solutions of the Yang–Baxter related to the corresponding double of Yangian; we also expect the non-ADE solutions (non simply laced or twisted) to be obtainable by appropriate folding. And one can even go beyond finite Dynkin diagrams, as in the AGT conjecture [13, part II].
- The gauge group can be chosen of type other than GL . In particular type C (symplectic) gauge groups should lead to systems with boundaries, i.e., solutions of the reflection equation (see the related work [20]), and to solutions of the q KZ equation in other types (in the sense of [1]). However no VO interpretation is known in type other than A.

Finally, this work should be extended to K-theory and possibly to elliptic cohomology. Also, it would be interesting to reinterpret it in the context of the gauge theory/integrable systems correspondence.

APPENDIX A. A SIMPLE EXAMPLE

Consider the quiver of type A_3 :

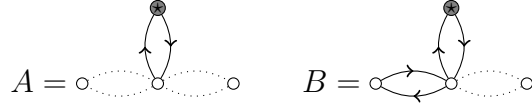


where N is an even integer, the white dots are the V_a , the gray dot represents W_2 (all other W_a are zero), and the arrows represent linear maps.

We find

$$\begin{aligned} \mu &= N\omega_2, & m &= \underbrace{(2, \dots, 2)}_N \\ \lambda &= 0, & \ell &= \underbrace{(4, \dots, 4)}_{N/2} \end{aligned}$$

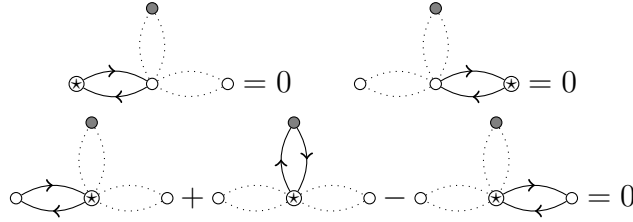
We claim that the ring of G_v -invariant functions has generators



(where the picture represents the product of operators along the paths, starting and ending at the marked vertex) and relations

$$B(A^2 + B) = (A^2 + B)B = A^3 + AB + BA = 0$$

which are implied by the moment maps conditions



For example, $A^2 + B = \text{diagram}$ and then

$$B(A^2 + B) = \text{diagram with labels 1-8} = - \text{diagram with labels 1-8} + \text{diagram with labels 1-8} = 0$$

where the labels indicate the ordering of steps of paths.

For $\lambda = 0$, we expect these to be all the relations (for general λ , i.e., lower values of the v 's, we expect other relations restricting the ranks of A and B).

In order to check this statement, we use the isomorphism with the Mirkovic–Vybornov slice. Here $M = 2N$, the nilpotent orbit closure is $\overline{\mathcal{O}_\ell} = \{X \in M \times M, X^4 = 0\}$, and the slice

is

$$\mathcal{T}_\mu = \left\{ \begin{array}{|cc|cc|c|} \hline 0 & 1 & 0 & 0 & \cdots \\ \hline \star & \star & \star & \star & \cdots \\ \hline 0 & 0 & 0 & 1 & \cdots \\ \hline \star & \star & \star & \star & \cdots \\ \hline \vdots & \vdots & \vdots & \vdots & \ddots \\ \hline \end{array} \right\} \cong \left\{ \begin{array}{c} N \quad N \\ N \quad \begin{bmatrix} 0 & 1 \\ B & A \end{bmatrix} \end{array} \right\}$$

Writing $\begin{pmatrix} 0 & 1 \\ B & A \end{pmatrix}^4 = 0$ results in the same equations as before.

In conclusion,

$$\mathfrak{M}_0 = \{A, B \text{ } N \times N \text{ matrices} : B(A^2 + B) = (A^2 + B)B = A^3 + AB + BA = 0\}$$

Similarly, one has

$$\mathfrak{Z}_0 = \{A, B \text{ } N \times N \text{ strict upper triangular matrices} :$$

$$B(A^2 + B) = (A^2 + B)B = A^3 + AB + BA = 0\}$$

$T \cong (\mathbb{C}^\times)^N$ acts by simultaneous conjugation of A and B , whereas the extra circle \mathbb{C}^\times acts by $A \mapsto t^2 A$, $B \mapsto t^4 B$.

Let us now further specialize to $N = 4$. Using for example Macaulay2 [6], we find that \mathfrak{Z}_0 has three components (which matches the dimension of $(L_{\omega_2}^{\otimes 4})^{SL(4)}$):

$$\mathfrak{Z}_{0, \begin{smallmatrix} \boxed{12} \\ \boxed{12} \\ \boxed{34} \\ \boxed{34} \end{smallmatrix}} = \{A, B : A_{1,2} = A_{3,4} = B_{1,2} = B_{3,4} = 0\}$$

$$\mathfrak{Z}_{0, \begin{smallmatrix} \boxed{12} \\ \boxed{13} \\ \boxed{24} \\ \boxed{34} \end{smallmatrix}} = \{A, B : B_{1,2} = B_{2,3} = B_{3,4} = (A^3 + AB + BA)_{1,4} = 0\}$$

$$\mathfrak{Z}_{0, \begin{smallmatrix} \boxed{13} \\ \boxed{13} \\ \boxed{24} \\ \boxed{24} \end{smallmatrix}} = \{A, B : A_{2,3} = B_{2,3} = (AB + BA)_{1,4} = (B^2)_{1,4} = 0\}$$

with multidegrees

$$\Psi_{\begin{smallmatrix} \boxed{12} \\ \boxed{12} \\ \boxed{34} \\ \boxed{34} \end{smallmatrix}} = (\hbar + z_1 - z_2)(\hbar + z_3 - z_4)(2\hbar + z_1 - z_2)(2\hbar + z_3 - z_4)$$

$$\Psi_{\begin{smallmatrix} \boxed{12} \\ \boxed{13} \\ \boxed{24} \\ \boxed{34} \end{smallmatrix}} = (2\hbar + z_1 - z_2)(2\hbar + z_2 - z_3)(2\hbar + z_3 - z_4)(3\hbar + z_1 - z_4)$$

$$\Psi_{\begin{smallmatrix} \boxed{13} \\ \boxed{13} \\ \boxed{24} \\ \boxed{24} \end{smallmatrix}} = (\hbar + z_2 - z_3)(2\hbar + z_2 - z_3)(3\hbar + z_1 - z_4)(4\hbar + z_1 - z_4)$$

It is not hard to show that the equations

$$\tau_i \Psi = \check{R}_i(z_i - z_{i+1}) \Psi, \quad i = 1, \dots, 3$$

define uniquely the R -matrices

$$\check{R}_1(z) = \check{R}_3(z) = \begin{pmatrix} \frac{(h-z)(2h-z)}{(h+z)(2h+z)} & 0 & 0 \\ \frac{z(2h-z)}{(h+z)(2h+z)} & \frac{2h-z}{2h+z} & 0 \\ \frac{-z(h-z)}{(h+z)(2h+z)} & \frac{2z}{2h+z} & 1 \end{pmatrix}$$

$$\check{R}_2(z) = \begin{pmatrix} 1 & \frac{2z}{2h+z} & \frac{-z(h-z)}{(h+z)(2h+z)} \\ 0 & \frac{2h-z}{2h+z} & \frac{z(2h-z)}{(h+z)(2h+z)} \\ 0 & 0 & \frac{(h-z)(2h-z)}{(h+z)(2h+z)} \end{pmatrix}$$

and that these satisfy Eqs. (1–3).

Furthermore, Ψ satisfies the remarkable cyclicity relation (Eq. (18))

$$\Psi(z_2, z_3, z_4, z_1 + 5\hbar) = \rho \Psi(z_1, z_2, z_3, z_4)$$

where $\rho = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$. (the fact that $\rho^2 = 1$ explains that $\check{R}_1(z) = \check{R}_3(z)$.)

Finally, Ψ satisfies the wheel condition:

$$\Psi(z, z+2\hbar, z+4\hbar, \cdot) = \Psi(z, z+2\hbar, \cdot, z+4\hbar) = \Psi(z, \cdot, z+2\hbar, z+4\hbar) = \Psi(\cdot, z, z+2\hbar, z+4\hbar) = 0$$

In order to switch to the stable basis, one must deform \mathfrak{M}_0 and \mathfrak{Z}_0 by taking the fiber at generic values of the moment map, or equivalently by deforming the nilpotent orbit closure $\{X^4 = 0\}$ to the regular orbit $\{\prod_{a=1}^4 (X - t_a) = 0, \det(x - X) = \prod_{a=1}^4 (x - t_a)^{\lambda_a}\}$ [11]. The equations deform into

$$\begin{aligned} A^2B + B^2 - e_1AB + e_2B + e_4 &= 0 \\ BA^2 + B^2 - e_1BA + e_2B + e_4 &= 0 \\ A^3 + AB + BA - e_1(A^2 + B) + e_2A - e_3 &= 0 \end{aligned}$$

where the e_i are the elementary symmetric polynomials of the t_i . The deformation \mathfrak{Z}_t of \mathfrak{Z}_0 corresponds to taking A and B to be upper triangular (not strict upper triangular), the diagonal entries encoding the stable basis components; in the present case, the eigenvalues of A are $t_i + t_j$, $1 \leq i < j \leq 4$, corresponding to the $GL(4)$ weights on L_{ω_2} . In order to select the weight space, one must either keep only the top-dimensional components, or impose the extra constraint on the characteristic polynomial of X mentioned above.

The coefficients of the change of basis are obtained by taking the flat limit $t_i \rightarrow 0$: each limit $\mathfrak{Z}'_{0,\alpha}$ of an irreducible component $\mathfrak{Z}'_{t,\alpha}$ of \mathfrak{Z}_t is a union of $\mathfrak{Z}_{0,\beta}$ with multiplicity $|c_\alpha^\beta|$. Here we shall not write down all of the c_α^β explicitly because already in size 4, the zero weight space of $L_{\omega_2}^{\otimes 4}$ has dimension 90. Instead we give only one component corresponding to $\alpha = (\{1, 2\}, \{1, 3\}, \{2, 4\}, \{3, 4\})$:

$$\begin{aligned} \mathfrak{Z}'_{t,\alpha} = \{A, B : A_{i,i} &= \sum_{a \in \alpha_i} t_a, B_{i,i} = - \prod_{a \in \alpha_i} t_a, \\ B_{2,3}A_{3,4} + (t_3 - t_2)B_{2,4} + t_3A_{2,3}A_{3,4} + t_3(t_3 - t_2)A_{2,4} &= 0 \\ A_{1,2}B_{2,3} + (t_2 - t_3)B_{1,3} + t_2A_{1,2}A_{2,3} + t_2(t_2 - t_3)A_{1,3} &= 0 \\ A_{1,2}B_{2,4} + B_{1,3}A_{3,4} + A_{1,2}A_{2,3}A_{3,4} + t_2A_{1,3}A_{3,4} + t_3A_{1,2}A_{2,4} &= 0 \} \end{aligned}$$

The $t_i \rightarrow 0$ limit $\mathfrak{Z}'_{0,\alpha}$ is the union of $\mathfrak{Z}_{0, \begin{smallmatrix} 12 \\ 12 \\ 34 \\ 34 \end{smallmatrix}}$ and $\mathfrak{Z}_{0, \begin{smallmatrix} 12 \\ 13 \\ 24 \\ 34 \end{smallmatrix}}$, each with multiplicity one.

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